

Qualitative analysis of some models of delay differential equations

Sebastián Buedo Fernández

September 9, 2021

PhD Thesis, DDays 2021

Supervisors: Eduardo Liz Marzán (UVigo)

Rosana Rodríguez López (USC)



FACULDADE DE MATEMÁTICAS



The **evolution** of some phenomena depends on their **history**.

$$x'(t) = f(t, x_t),$$

where x_t denotes the history of x up to time t .

The **evolution** of some phenomena depends on their **history**.

$$x'(t) = f(t, x_t),$$

where x_t denotes the history of x up to time t . Some also fall into the dynamics of **production and destruction** (Mackey & Glass, 1982):

The **evolution** of some phenomena depends on their **history**.

$$x'(t) = f(t, x_t),$$

where x_t denotes the history of x up to time t . Some also fall into the dynamics of **production and destruction** (Mackey & Glass, 1982):

$$x'(t) = -d(t, x_t) + p(t, x_t)$$

The **evolution** of some phenomena depends on their **history**.

$$x'(t) = f(t, x_t),$$

where x_t denotes the history of x up to time t . Some also fall into the dynamics of **production and destruction** (Mackey & Glass, 1982):

$$x'(t) = -a(t)x(t) + p(t, x_t)$$

In this **PhD thesis**:

- We provide **theoretical results** concerning the **behaviour** of the solutions of the former equation.
- We **apply** those and other well-known results to study equations that **generalise** several widely-used models.

The **evolution** of some phenomena depends on their **history**.

$$x'(t) = f(t, x_t),$$

where x_t denotes the history of x up to time t . Some also fall into the dynamics of **production and destruction** (Mackey & Glass, 1982):

$$x'(t) = -a(t)x(t) + p(t, x_t)$$

In this **PhD thesis**:

- We provide **theoretical results** concerning the **behaviour** of the solutions of the former equation.
- We **apply** those and other well-known results to study equations that **generalise** several widely-used models.

In this **talk**, we focus on **gamma-models**.

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.
- We provide a theoretical framework to make their study in a methodic way.

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.
- We provide a theoretical framework to make their study in a methodic way.
- We combine known results to extend the global attractivity conditions available in the literature for particular models.

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.
- We provide a theoretical framework to make their study in a methodic way.
- We combine known results to extend the global attractivity conditions available in the literature for particular models.

What is a **gamma-model**?

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.
- We provide a theoretical framework to make their study in a methodic way.
- We combine known results to extend the global attractivity conditions available in the literature for particular models.

What is a **gamma-model**?

Quinn & Deriso, 1999; Liz, 2018 (x2).

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.
- We provide a theoretical framework to make their study in a methodic way.
- We combine known results to extend the global attractivity conditions available in the literature for particular models.

What is a **gamma-model**?



S. B.-F., E. Liz.

On the stability properties of a delay differential neoclassical model of economic growth.

Electronic Journal of the Qualitative Theory of Differential Equations 2018, no. 43, 1–14 (2018).

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.
- We provide a theoretical framework to make their study in a methodic way.
- We combine known results to extend the global attractivity conditions available in the literature for particular models.

What is a **gamma-model**?



S. B.-F.

On the gamma-logistic map and applications to a delayed neoclassical model of economic growth.

Nonlinear Dynamics 96, 219–227 (2019).

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.
- We provide a theoretical framework to make their study in a methodic way.
- We combine known results to extend the global attractivity conditions available in the literature for particular models.

What is a **gamma-model**?



E. Liz, S. B.-F.

A new formula to get sharp global stability criteria for one-dimensional discrete-time models.

Qualitative Theory of Dynamical Systems 18, 813–824 (2019).

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.
- We provide a theoretical framework to make their study in a methodic way.
- We combine known results to extend the global attractivity conditions available in the literature for particular models.

What is a **gamma-model**?

$$x'(t) = -ax(t) + f(x(t - \tau))$$

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.
- We provide a theoretical framework to make their study in a methodic way.
- We combine known results to extend the global attractivity conditions available in the literature for particular models.

What is a **gamma-model**?

$$x'(t) = -ax(t) + f(x(t - \tau))$$

If $f(x) = x^\gamma h(x)$, where $\gamma \geq 0$ and h is nonincreasing, then the former equation is a **delay differential gamma-model**.

In the part related to **gamma-models**:

- We generalise several models appearing in Economics, Biology or Ecology.
- We provide a theoretical framework to make their study in a methodic way.
- We combine known results to extend the global attractivity conditions available in the literature for particular models.

What is a **gamma-model**?

$$x'(t) = -ax(t) + f(x(t - \tau))$$

If $f(x) = x^\gamma h(x)$, where $\gamma \geq 0$ and h is nonincreasing, then the former equation is a **delay differential gamma-model**.

Analogously, if $F(x) = x^\gamma H(x)$, where $\gamma \geq 0$ and H is nonincreasing, the difference equation $x_{n+1} = F(x_n)$ is a **discrete gamma-model**.

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

An application in **Economics**:

Neoclassical model of economic growth

Solow, 1956; Barro & Sala-i-Martin, 2004; Day, 1982; Matsumoto & Szidarovszky, 2011-2013.

The **capital-labour rate** $x(t)$ is modelled under the equation above.

- γ is the **output elasticity of capital**.
- h is the term related to **pollution effects** due to huge concentrations of capital.
- τ stands for the **production lag**.

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

An application in **Ecology**:

Nicholson's blowflies model

Gurney, Blythe & Nisbet, 1980

The **size** of the **population** of *Lucilia cuprinia* $x(t)$ is modelled under the equation above with the limit case $\gamma = 1$.

- $h(x) = \beta e^{-\delta x}$ ($\beta, \delta > 0$) is the **per-capita growth factor**.
- τ represents the **time** required for new individuals to **achieve the adulthood**.

If the constraint $\gamma = 1$ is not imposed, it modules the competition between individuals.

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$$\gamma \in (0, 1), h : [0, \infty) \rightarrow (0, \infty) \text{ nonincreasing}$$

An application in **Biology**:

Hematopoiesis

Mackey & Glass, 1977; Mitkowski, 2011.

The **density** of a certain class of **blood cells** $x(t)$ is modelled under the equation above for the cases $\gamma = 0$ and $\gamma = 1$.

- $h(x) = \frac{\beta}{1 + \delta x^m}$ ($\beta, \delta, m > 0$).
- τ represents the **time** required for cellular production.

Generally speaking, γ represents the disturbance on the healthy cellular production.

$$x'(t) = -ax(t) + f(x(t - \tau))$$

This equation is written in terms of three items:

- $a > 0$ is the **destruction rate**.
- $f : I \subset \mathbb{R} \rightarrow \mathbb{R}$ is the **production function**.
- $\tau > 0$ is the **discrete delay**.

$$x'(t) = -ax(t) + f(x(t - \tau))$$

This equation is written in terms of the triples (a, f, τ) .

For large values of τ , the previous equation might be seen as a **singular perturbation** of the (cont.-time) **difference equation**

$$x'(t) = -ax(t) + f(x(t - \tau))$$

This equation is written in terms of the triples (a, f, τ) .

For large values of τ , the previous equation might be seen as a **singular perturbation** of the (cont.-time) **difference equation**

$$x'(t) = -ax(t) + f(x(t - \tau))$$

This equation is written in terms of the triples (a, f, τ) .

For large values of τ , the previous equation might be seen as a **singular perturbation** of the (cont.-time) **difference equation**

$$x'(t) = -ax(t) + f(x(t - \tau))$$

This equation is written in terms of the triples (a, f, τ) .

For large values of τ , the previous equation might be seen as a **singular perturbation** of the (cont.-time) **difference equation**

$$x'(t) = -ax(t) + f(x(t - \tau))$$

This equation is written in terms of the triples (a, f, τ) .

For large values of τ , the previous equation might be seen as a **singular perturbation** of the (cont.-time) **difference equation**

$$x'(t) = -ax(t) + f(x(t - \tau))$$

This equation is written in terms of the triples (a, f, τ) .

For large values of τ , the previous equation might be seen as a **singular perturbation** of the (cont.-time) **difference equation**

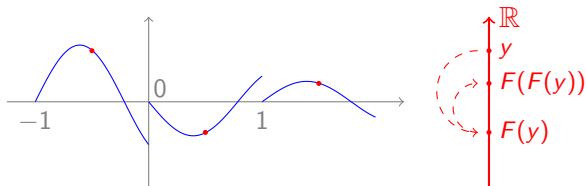
$$x(t) = \frac{1}{a} f(x(t - 1)) =: F(x(t - 1)).$$

$$x'(t) = -ax(t) + f(x(t - \tau))$$

This equation is written in terms of the triples (a, f, τ) .

For large values of τ , the previous equation might be seen as a **singular perturbation** of the (cont.-time) **difference equation**

$$x(t) = \frac{1}{a} f(x(t - 1)) =: F(x(t - 1)).$$



$$x'(t) = -ax(t) + f(x(t - \tau))$$

This equation is written in terms of the triples (a, f, τ) .

For large values of τ , the previous equation might be seen as a **singular perturbation** of the (cont.-time) **difference equation**

$$x(t) = \frac{1}{a} f(x(t - 1)) =: F(x(t - 1)).$$

whose solutions are governed by

$$x_{n+1} = F(x_n)$$

(Mallet-Paret & Nussbaum, 1986; Ivanov & Sharkovsky, 1992).

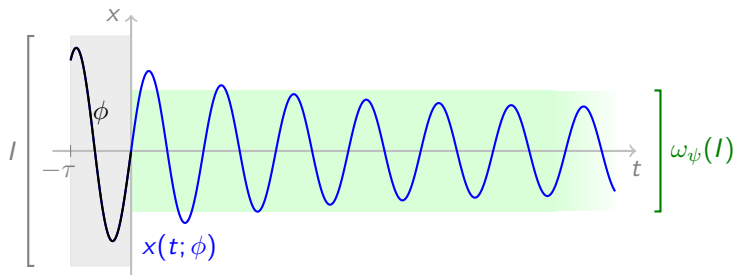
$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E)$$

Equation (E) generates a semiflow $\varphi : \mathbb{R}_+ \times C_I \rightarrow C_I$
 $x_{n+1} = F(x_n)$ generates a semiflow $\psi : \mathbb{Z}_+ \times I \rightarrow I$.

$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E)$$

Equation (E) generates a semiflow $\varphi : \mathbb{R}_+ \times C_I \rightarrow C_I$
 $x_{n+1} = F(x_n)$ generates a semiflow $\psi : \mathbb{Z}_+ \times I \rightarrow I$.

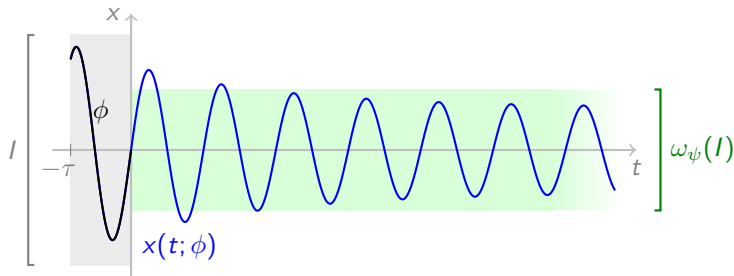
$$\left[\liminf_{t \rightarrow \infty} x(t; \phi), \limsup_{t \rightarrow \infty} x(t; \phi) \right] \subset \omega_\psi(I), \quad \forall \phi \in C_I.$$



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E)$$

Equation (E) generates a semiflow $\varphi : \mathbb{R}_+ \times C_I \rightarrow C_I$
 $x_{n+1} = F(x_n)$ generates a semiflow $\psi : \mathbb{Z}_+ \times I \rightarrow I$.

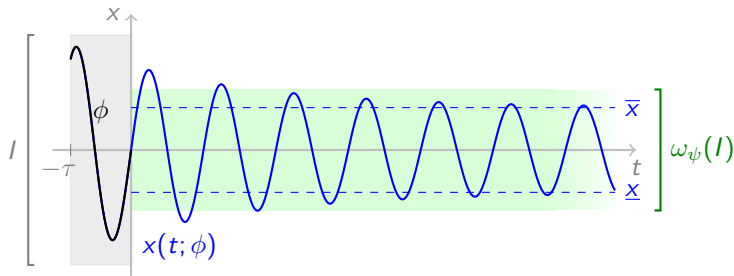
$$[\underline{x}, \bar{x}] \subset \omega_\psi(I), \quad \forall \phi \in C_I.$$



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E)$$

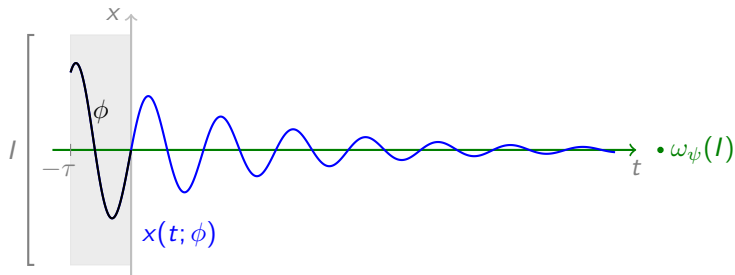
Equation (E) generates a semiflow $\varphi : \mathbb{R}_+ \times C_I \rightarrow C_I$
 $x_{n+1} = F(x_n)$ generates a semiflow $\psi : \mathbb{Z}_+ \times I \rightarrow I$.

$$[\underline{x}, \bar{x}] \subset \omega_\psi(I), \quad \forall \phi \in C_I.$$



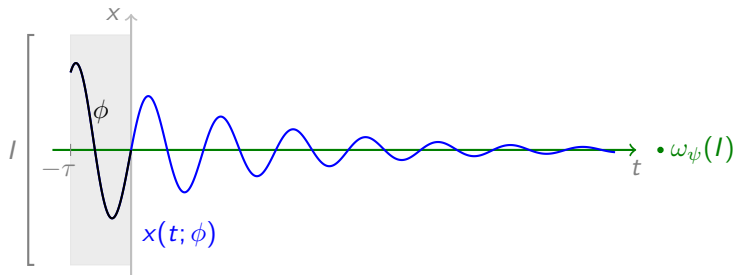
$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E)$$

Equation (E) generates a semiflow $\varphi : \mathbb{R}_+ \times C_I \rightarrow C_I$
 $x_{n+1} = F(x_n)$ generates a semiflow $\psi : \mathbb{Z}_+ \times I \rightarrow I$.



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E)$$

Equation (E) generates a semiflow $\varphi : \mathbb{R}_+ \times C_I \rightarrow C_I$
 $x_{n+1} = F(x_n)$ generates a semiflow $\psi : \mathbb{Z}_+ \times I \rightarrow I$.



Corollary (Mallet-Paret & Nussbaum, 1986)

Let I be a compact interval and $F : I \rightarrow I$ be a continuous function. If p is globally attracting for $x_{n+1} = F(x_n)$, then p is globally attracting for (E).

$$x'(t) = -ax(t) + f(x(t - \tau))$$

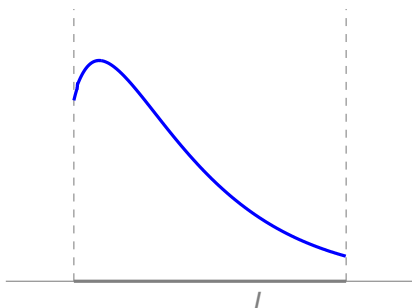
Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

$$x'(t) = -ax(t) + f(x(t - \tau))$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

We should handle appropriate hypotheses on the triples (a, f, τ) :

(T1) $a, \tau \in \mathbb{R}^+$, $f \in \mathcal{C}^1(I, \mathbb{R})$, $I \subset \mathbb{R}$ is a non-empty open interval

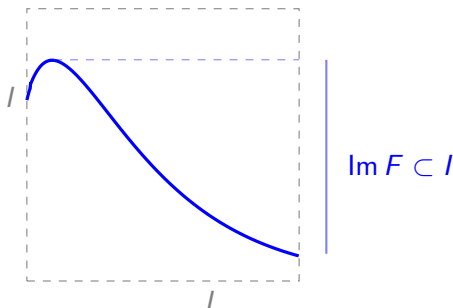


$$x'(t) = -ax(t) + f(x(t - \tau))$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

We should handle appropriate hypotheses on the triples (a, f, τ) :

(T2) $\frac{f}{a} : I \rightarrow I$ is well-defined

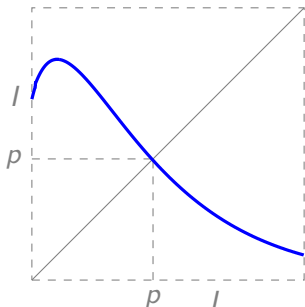


$$x'(t) = -ax(t) + f(x(t - \tau))$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

We should handle appropriate hypotheses on the triples (a, f, τ) :

(T3) $F(x) = \frac{f(x)}{a} = x$ has a unique solution $p \in I$

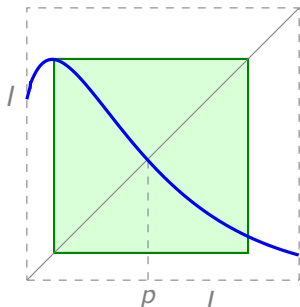


$$x'(t) = -ax(t) + f(x(t - \tau))$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

We should handle appropriate hypotheses on the triples (a, f, τ) :

(T4) $K \subset I$ is a non-degenerate compact interval that is globally attracting for $F = \frac{f}{a}$



$$x'(t) = -ax(t) + f(x(t - \tau))$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Characterization of its existence:

Coppel, 1955; Franco, Perán & Segura, 2018

$$x'(t) = -ax(t) + f(x(t - \tau))$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Characterization of its existence:

Coppel, 1955; Franco, Perán & Segura, 2018

Theorem (e.g., Franco, Perán & Segura, 2020)

Let $F : I \rightarrow I$ be a continuous function and $p \in I$ be the unique fixed point of F . Then p is GAS for F if and only if

$$x'(t) = -ax(t) + f(x(t - \tau))$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Characterization of its existence:

Coppel, 1955; Franco, Perán & Segura, 2018

Theorem (e.g., Franco, Perán & Segura, 2020)

Let $F : I \rightarrow I$ be a continuous function and $p \in I$ be the unique fixed point of F . Then p is GAS for F if and only if

$$(F^2(x) - x)(x - p) < 0, \quad \forall x \in I \setminus \{p\}.$$

$$x'(t) = -ax(t) + f(x(t - \tau))$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Characterization of its existence:

Coppel, 1955; Franco, Perán & Segura, 2018

Theorem (e.g., Franco, Perán & Segura, 2020)

Let $F : I \rightarrow I$ be a continuous function and $p \in I$ be the unique fixed point of F . Then p is GAS for F if and only if

$$([F \circ F](x) - x)(x - p) < 0, \quad \forall x \in I \setminus \{p\}.$$

$$x'(t) = -ax(t) + f(x(t - \tau))$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Characterization of its existence:

Coppel, 1955; Franco, Perán & Segura, 2018

Theorem (e.g., Franco, Perán & Segura, 2020)

Let $F : I \rightarrow I$ be a continuous function and $p \in I$ be the unique fixed point of F . Then p is GAS for F if and only if

$$(F(F(x)) - x)(x - p) < 0, \quad \forall x \in I \setminus \{p\}.$$

$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

Use the Schwarzian derivative! (Allwright, 1978; Singer, 1978)

$$SF(x) = \frac{F'''(x)}{F'(x)} - \frac{3}{2} \left(\frac{F''(x)}{F'(x)} \right)^2, \quad F'(x) \neq 0.$$

Maps F with negative Schwarzian derivative are of great interest:

$$\text{LAS} \implies \text{GAS}$$

Theorem (El-Morshedy & Jiménez López, 2008)

Let $F \in \mathcal{C}^3(I, I)$ be such that

$$(F(x) - x)(x - p) < 0, \quad \forall x \in I \setminus \{p\},$$

and having at most one critical point, which would be called c and would also satisfy $F''(c) \neq 0$.

Assume that one of the following two conditions holds:

- The function F satisfies $0 \leq F'(p) < 1$.
- The function F satisfies $-1 \leq F'(p) < 0$ and $SF(x) < 0$, for every $x \in I_*$, where
 - $I_* = I$, if there is no extremum,
 - $I_* = I \cap (c, \infty)$, if F attains a maximum value at c , and
 - $I_* = I \cap (-\infty, c)$, if F attains a minimum value at c .

Then the equilibrium p is globally attracting for F .

$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

El-Morshedy & Jiménez López, 2008

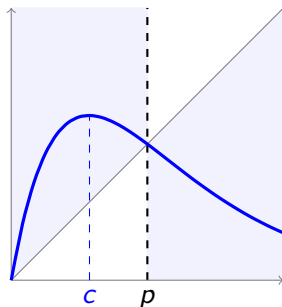
Hyp.:

$F \in \mathcal{C}^3(I, I)$ is such that

...

has at most one critical point c
(non-inflection)

...



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (EP)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

El-Morshedy & Jiménez López, 2008

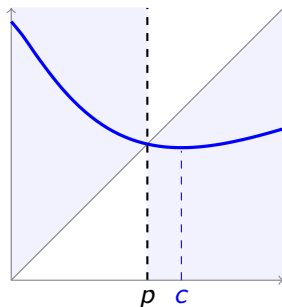
Hyp.:

$F \in \mathcal{C}^3(I, I)$ is such that

...

has at most one critical point c
(non-inflection)

...



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

El-Morshedy & Jiménez López, 2008

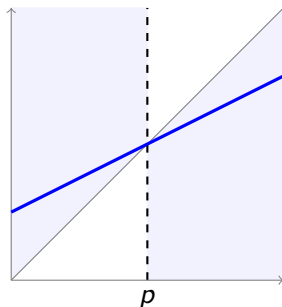
Hyp.:

$F \in \mathcal{C}^3(I, I)$ is such that

...

has at most one critical point c
(non-inflection)

...



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

El-Morshedy & Jiménez López, 2008

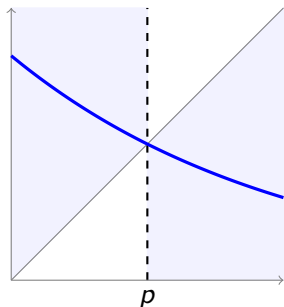
Hyp.:

$F \in \mathcal{C}^3(I, I)$ is such that

...

has at most one critical point c
(non-inflection)

...



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

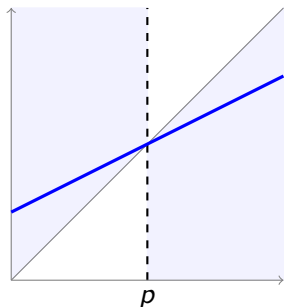
El-Morshedy & Jiménez López, 2008

Thesis:

p is **globally attracting** when

$$0 \leq F'(p) < 1$$

...



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

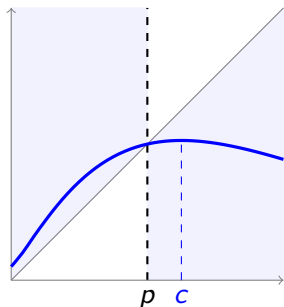
El-Morshedy & Jiménez López, 2008

Thesis:

p is **globally attracting** when

$$0 \leq F'(p) < 1$$

...



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

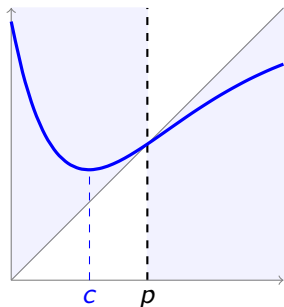
El-Morshedy & Jiménez López, 2008

Thesis:

p is **globally attracting** when

$$0 \leq F'(p) < 1$$

...



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

El-Morshedy & Jiménez López, 2008

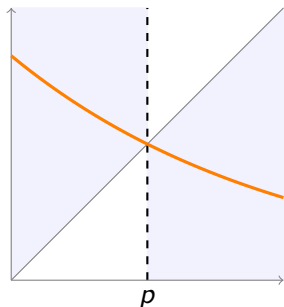
Thesis:

p is **globally attracting** when

...

$-1 \leq F'(p) < 0$, $SF < 0$ on I_*

(I_* subinterval of decrease)



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

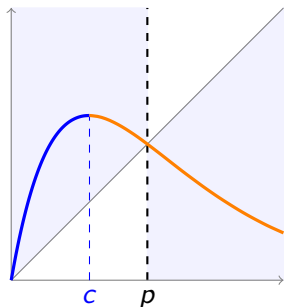
El-Morshedy & Jiménez López, 2008

Thesis:

p is **globally attracting** when

...

$-1 \leq F'(p) < 0$, $SF < 0$ on I_*
(I_* subinterval of decrease)



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (EP)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

Sufficient condition for its existence:

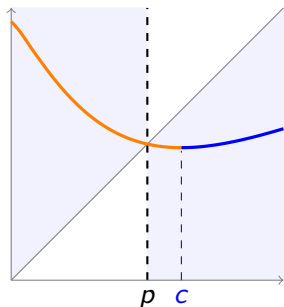
El-Morshedy & Jiménez López, 2008

Thesis:

p is **globally attracting** when

...

$-1 \leq F'(p) < 0$, $SF < 0$ on I_*
(I_* subinterval of decrease)



$$x'(t) = -ax(t) + f(x(t - \tau)) \quad (E_P)$$

Study the global dynamics of $x_{n+1} = F(x_n)$, where $F = \frac{f}{a}$.
In particular, does a **globally attracting equilibrium** exist?

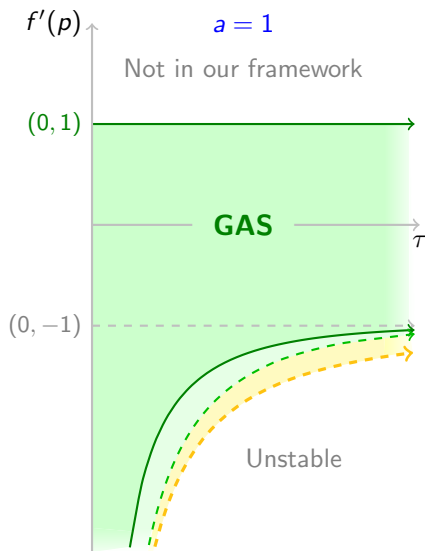
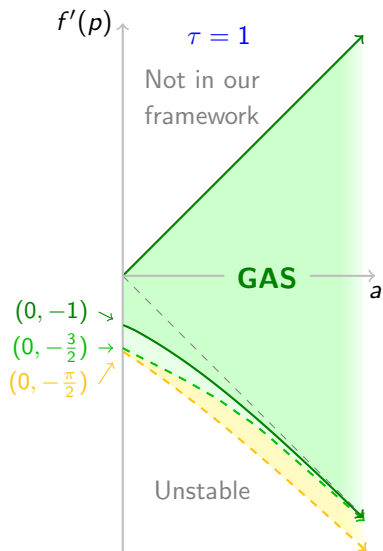
Sufficient condition for its existence:

Definition

Maps on the former context

- with $SF < 0$ on the interval of decrease are called **S_* -maps**.
[El-Morshedy & Jiménez López]
- with $SF < 0$ everywhere are called **S -maps**.
[Allwright, Singer]

Space of triples $(a, f'(p), \tau)$, with negativity-type hypothesis on Sf .



We analyse the **role** of $\gamma \in (0, 1)$ on the dynamics of $x_{n+1} = F(x_n)$, where $F(x) = \frac{1}{a}x^\gamma h(x)$, for **different choices of the function** h .

Theoretical framework

Theorem

Let $a > 0$ and $h : [0, \infty) \rightarrow (0, \infty)$ be a nonincreasing function of class \mathcal{C}^1 . Then, for each $\gamma \in (0, 1)$,

We analyse the **role** of $\gamma \in (0, 1)$ on the dynamics of $x_{n+1} = F(x_n)$, where $F(x) = \frac{1}{a}x^\gamma h(x)$, for **different choices of the function** h .

Theoretical framework

Theorem

Let $a > 0$ and $h : [0, \infty) \rightarrow (0, \infty)$ be a nonincreasing function of class C^1 . Then, for each $\gamma \in (0, 1)$,

[Unique equilibrium] there is a unique positive fixed point of the map F , namely $p := p(\gamma)$, which is the unique root of equation $p^{1-\gamma} = H(p)$;

We analyse the **role** of $\gamma \in (0, 1)$ on the dynamics of $x_{n+1} = F(x_n)$, where $F(x) = \frac{1}{a}x^\gamma h(x)$, for **different choices of the function** h .

Theoretical framework

Theorem

Let $a > 0$ and $h : [0, \infty) \rightarrow (0, \infty)$ be a nonincreasing function of class C^1 . Then, for each $\gamma \in (0, 1)$,

[Unique equilibrium] *there is a unique positive fixed point of the map F , namely $p := p(\gamma)$, which is the unique root of equation $p^{1-\gamma} = H(p)$;*

[Graph] $(F(x) - x)(x - p) < 0, \quad \forall x \in (0, \infty) \setminus \{p\}$;

We analyse the **role** of $\gamma \in (0, 1)$ on the dynamics of $x_{n+1} = F(x_n)$, where $F(x) = \frac{1}{a}x^\gamma h(x)$, for **different choices of the function** h .

Theoretical framework

Theorem

Let $a > 0$ and $h : [0, \infty) \rightarrow (0, \infty)$ be a nonincreasing function of class C^1 . Then, for each $\gamma \in (0, 1)$,

[Unique equilibrium] *there is a unique positive fixed point of the map F , namely $p := p(\gamma)$, which is the unique root of equation $p^{1-\gamma} = H(p)$;*

[Graph] $(F(x) - x)(x - p) < 0, \quad \forall x \in (0, \infty) \setminus \{p\}$;

[Value equilibrium] *one of the following cases holds:*

- $p(\gamma) < 1$ *is decreasing on $(0, 1)$, or, equivalently, $H(1) < 1$;*
- $p(\gamma) = 1$, *for every $\gamma \in (0, 1)$, or, equivalently, $H(1) = 1$;*
- $p(\gamma) > 1$ *is increasing on $(0, 1)$, or, equivalently, $H(1) > 1$;*

We analyse the **role** of $\gamma \in (0, 1)$ on the dynamics of $x_{n+1} = F(x_n)$, where $F(x) = \frac{1}{a}x^\gamma h(x)$, for **different choices of the function** h .

Theoretical framework

Theorem

Let $a > 0$ and $h : [0, \infty) \rightarrow (0, \infty)$ be a nonincreasing function of class C^1 . Then, for each $\gamma \in (0, 1)$,

[Unique equilibrium] *there is a unique positive fixed point of the map F , namely $p := p(\gamma)$, which is the unique root of equation $p^{1-\gamma} = H(p)$;*

[Graph] $(F(x) - x)(x - p) < 0, \quad \forall x \in (0, \infty) \setminus \{p\}$;

[Value equilibrium] *one of the following cases holds:*

- $p(\gamma) < 1$ *is decreasing on $(0, 1)$, or, equivalently, $H(1) < 1$;*
- $p(\gamma) = 1$, *for every $\gamma \in (0, 1)$, or, equivalently, $H(1) = 1$;*
- $p(\gamma) > 1$ *is increasing on $(0, 1)$, or, equivalently, $H(1) > 1$;*

[Local dynamics] $F'(p) = \gamma + p^\gamma H'(p) < 1$.

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

Lasota equation

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

Lasota equation

Pollution effects, $h(x) = \beta e^{-\delta x}$, $\beta, \delta > 0$.

$$x'(t) = -ax(t) + \beta x^\gamma(t - \tau) e^{-\delta x(t - \tau)} \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} x_n^\gamma e^{-\delta x_n} \quad (D)$$

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

Lasota equation

Pollution effects, $h(x) = \beta e^{-\delta x}$, $\beta, \delta > 0$.

$$x'(t) = -ax(t) + \beta x^\gamma(t - \tau) e^{-\delta x(t - \tau)} \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} x_n^\gamma e^{-\delta x_n} \quad (D)$$

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

Lasota equation

Pollution effects, $h(x) = \beta e^{-\delta x}$, $\beta, \delta > 0$.

$$x'(t) = -ax(t) + \beta x^\gamma(t - \tau) e^{-\delta x(t - \tau)} \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} x_n^\gamma e^{-\delta x_n} \quad (D)$$

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$$\gamma \in (0, 1), h : [0, \infty) \rightarrow (0, \infty) \text{ nonincreasing}$$

Lasota equation

Pollution effects, $h(x) = \beta e^{-\delta x}$, $\beta, \delta > 0$.

$$x'(t) = -ax(t) + \beta x^\gamma(t - \tau) e^{-\delta x(t - \tau)} \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} x_n^\gamma e^{-\delta x_n} \quad (D)$$

Theorem (B.-F. & Liz, 2018)

Let p be the unique equilibrium of (E). If

$$\frac{\beta}{a} \leq e^{\gamma+1} \left(\frac{\gamma+1}{\delta} \right)^{1-\gamma} \quad (*)$$

then,

$$\lim_{t \rightarrow \infty} x(t; \phi) = p, \quad \forall \phi \in C_{(0, \infty)}$$

regardless the value of τ . Condition (*) is the **sharpest delay-independent stability condition** for (E).

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$$\gamma \in (0, 1), h : [0, \infty) \rightarrow (0, \infty) \text{ nonincreasing}$$

Lasota equation

Pollution effects, $h(x) = \beta e^{-\delta x}$, $\beta, \delta > 0$.

$$x'(t) = -ax(t) + \beta x^\gamma(t - \tau) e^{-\delta x(t - \tau)} \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} x_n^\gamma e^{-\delta x_n} \quad (D)$$

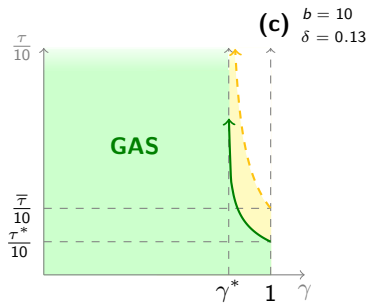
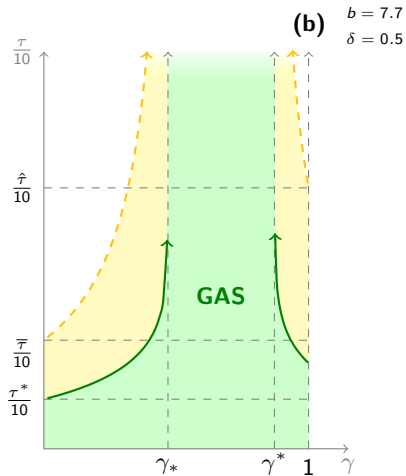
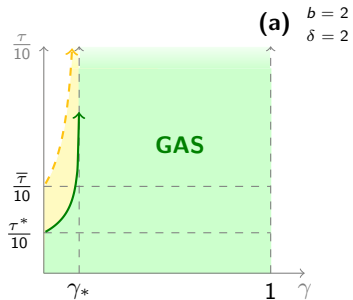
Theorem (B.-F. & Liz, 2018)

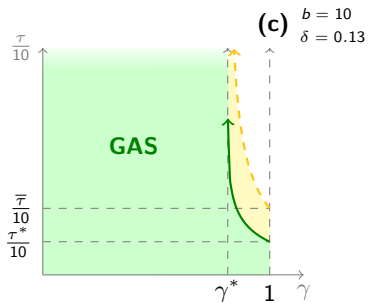
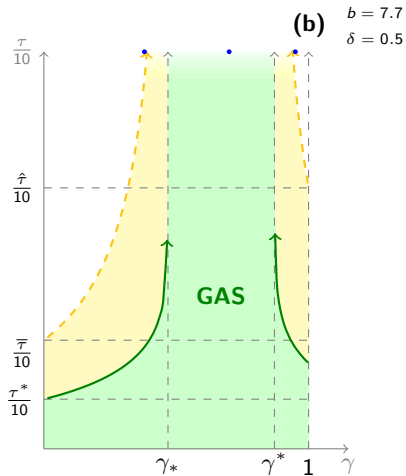
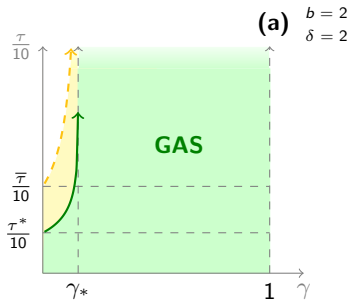
Let p be the unique equilibrium of (E). If

$$\frac{\beta}{a} \leq e^{\gamma + \frac{1}{1 - e^{-a\tau}}} \left(\frac{\gamma + \frac{1}{1 - e^{-a\tau}}}{\delta} \right)^{1 - \gamma}$$

then,

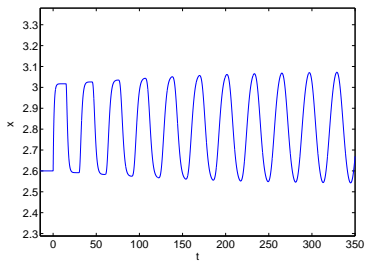
$$\lim_{t \rightarrow \infty} x(t; \phi) = p, \quad \forall \phi \in C_{(0, \infty)}.$$





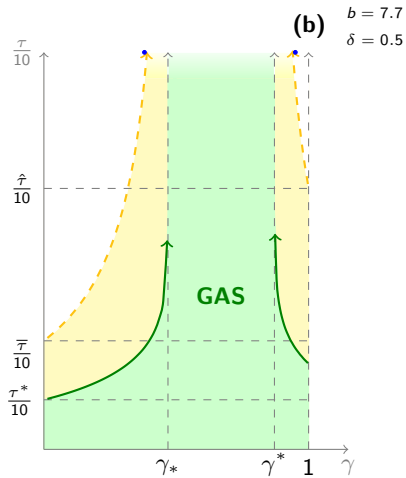
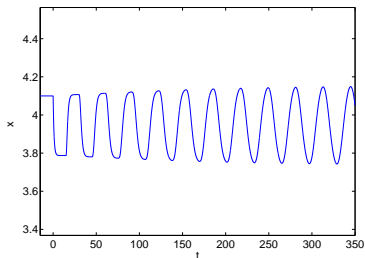
$$\gamma = 0.38$$

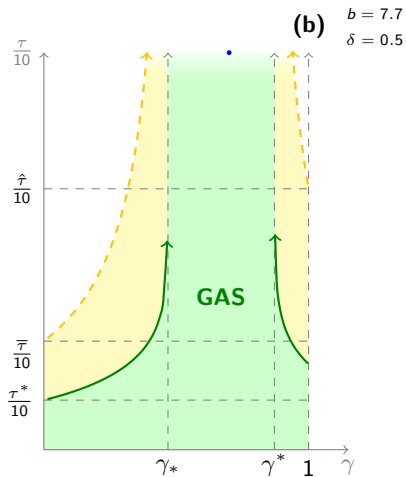
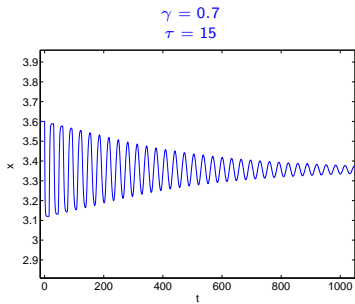
$$\tau = 15$$



$$\gamma = 0.95$$

$$\tau = 15$$





$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

γ -logistic DDE

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$$\gamma \in (0, 1), h : [0, \infty) \rightarrow (0, \infty) \text{ nonincreasing}$$

γ -logistic DDE

Pollution effects, $h(x) = \beta(1 - x)$, $\beta > 0$.

$$x'(t) = -ax(t) + \beta x^\gamma(t - \tau)(1 - x(t - \tau)) \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} x_n^\gamma (1 - x_n) \quad (D)$$

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$$\gamma \in (0, 1), h : [0, \infty) \rightarrow (0, \infty) \text{ nonincreasing}$$

γ -logistic DDE

Pollution effects, $h(x) = \beta(1 - x)$, $\beta > 0$.

$$x'(t) = -ax(t) + \beta x^\gamma(t - \tau)(1 - x(t - \tau)) \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} x_n^\gamma (1 - x_n) \quad (D)$$

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$$\gamma \in (0, 1), h : [0, \infty) \rightarrow (0, \infty) \text{ nonincreasing}$$

γ -logistic DDE

Pollution effects, $h(x) = \beta(1 - x)$, $\beta > 0$.

$$x'(t) = -ax(t) + \beta x^\gamma(t - \tau)(1 - x(t - \tau)) \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} x_n^\gamma (1 - x_n) \quad (D)$$

Corollary

The unique positive equilibrium p of (E) decreases for increasing $\gamma \in (0, 1)$.

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$$\gamma \in (0, 1), h : [0, \infty) \rightarrow (0, \infty) \text{ nonincreasing}$$

γ -logistic DDE

Pollution effects, $h(x) = \beta(1 - x)$, $\beta > 0$.

$$x'(t) = -ax(t) + \beta x^\gamma(t - \tau)(1 - x(t - \tau)) \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} x_n^\gamma (1 - x_n) \quad (D)$$

Theorem (B.-F., 2019)

Let the consistency condition hold and p be the unique equilibrium of (E). If

$$\frac{\beta}{a} \leq \gamma + 1 \left(\frac{\gamma + 2}{\gamma + 1} \right)^\gamma \quad (*)$$

then,

$$\lim_{t \rightarrow \infty} x(t; \phi) = p, \quad \forall \phi \in C_{(0, \infty)}$$

regardless the value of τ . Condition (*) is the **sharpest delay-independent stability condition** for (E).

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$$\gamma \in (0, 1), h : [0, \infty) \rightarrow (0, \infty) \text{ nonincreasing}$$

γ -logistic DDE

Pollution effects, $h(x) = \beta(1 - x)$, $\beta > 0$.

$$x'(t) = -ax(t) + \beta x^\gamma(t - \tau)(1 - x(t - \tau)) \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} x_n^\gamma (1 - x_n) \quad (D)$$

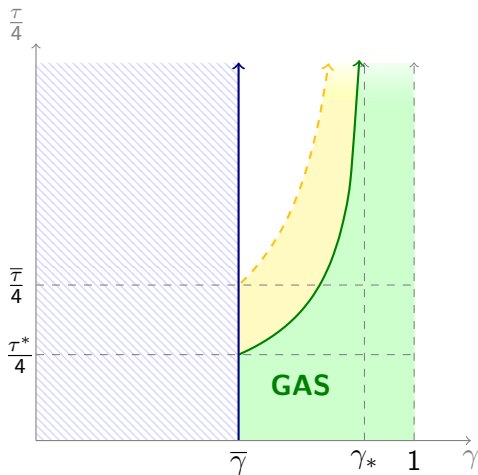
Theorem (B.-F., 2019)

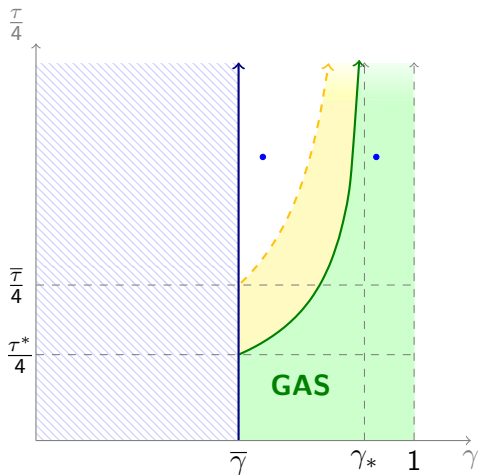
Let the consistency condition hold and p be the unique equilibrium of (E). If

$$\frac{\beta}{a} \leq \left(\gamma + \frac{1}{1 - e^{-a\tau}} \right) \left(\frac{\gamma + 1 + \frac{1}{1 - e^{-a\tau}}}{\gamma + \frac{1}{1 - e^{-a\tau}}} \right)^\gamma$$

then,

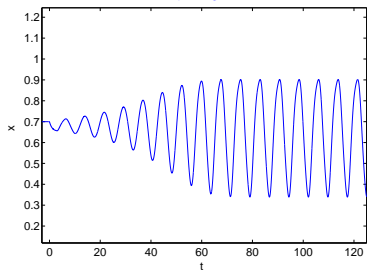
$$\lim_{t \rightarrow \infty} x(t; \phi) = p, \quad \forall \phi \in C_{(0, \infty)}.$$





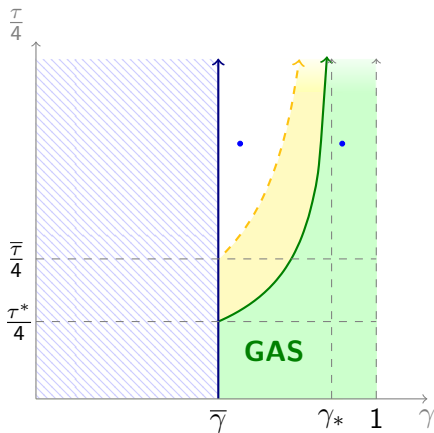
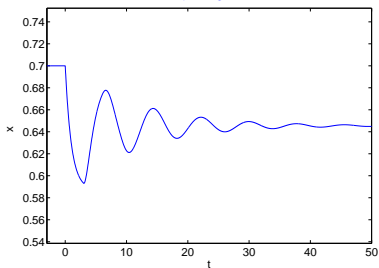
$$\gamma = 0.6$$

$$\tau = 3$$



$$\gamma = 0.9$$

$$\tau = 3$$



$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

γ -Mackey-Glass DDE

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

γ -Mackey-Glass DDE

Pollution effects, $h(x) = \frac{\beta}{a} \frac{1}{1 + \delta x^m}$, $\beta, \delta, m > 0$.

$$x'(t) = -ax(t) + \frac{\beta x^\gamma(t - \tau)}{1 + \delta x^m(t - \tau)} \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} \frac{x_n^\gamma}{1 + \delta x_n^m} \quad (D)$$

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$\gamma \in (0, 1)$, $h : [0, \infty) \rightarrow (0, \infty)$ nonincreasing

γ -Mackey-Glass DDE

Pollution effects, $h(x) = \frac{\beta}{a} \frac{1}{1 + \delta x^m}$, $\beta, \delta, m > 0$.

$$x'(t) = -ax(t) + \frac{\beta x^\gamma(t - \tau)}{1 + \delta x^m(t - \tau)} \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} \frac{x_n^\gamma}{1 + \delta x_n^m} \quad (D)$$

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$$\gamma \in (0, 1), h : [0, \infty) \rightarrow (0, \infty) \text{ nonincreasing}$$

γ -Mackey-Glass DDE

Pollution effects, $h(x) = \frac{\beta}{a} \frac{1}{1 + \delta x^m}$, $\beta, \delta, m > 0$.

$$x'(t) = -ax(t) + \frac{\beta x^\gamma(t - \tau)}{1 + \delta x^m(t - \tau)} \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} \frac{x_n^\gamma}{1 + \delta x_n^m} \quad (D)$$

Theorem (B.-F. & Liz, 2018)

Let $m = 1$ and p be the unique equilibrium of (E). Then,

$$\lim_{t \rightarrow \infty} x(t; \phi) = p, \quad \forall \phi \in C_{(0, \infty)}.$$

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau))$$

$$\gamma \in (0, 1), h : [0, \infty) \rightarrow (0, \infty) \text{ nonincreasing}$$

γ -Mackey-Glass DDE

Pollution effects, $h(x) = \frac{\beta}{a} \frac{1}{1 + \delta x^m}$, $\beta, \delta, m > 0$.

$$x'(t) = -ax(t) + \frac{\beta x^\gamma(t - \tau)}{1 + \delta x^m(t - \tau)} \quad (E)$$

$$x_{n+1} = \frac{\beta}{a} \frac{x_n^\gamma}{1 + \delta x_n^m} \quad (D)$$

Theorem (B.-F. & Liz, 2018)

Let $m = 1$ and p be the unique equilibrium of (E). Then,

$$\lim_{t \rightarrow \infty} x(t; \phi) = p, \quad \forall \phi \in C_{(0, \infty)}.$$

What happens if $m \neq 1$?

Key idea: a change of variables from Liz, 2007.

$$\begin{array}{ccc} x_{n+1} = F(x_n) & & y_{n+1} = T(y_n) \\ F(x) = x^\gamma H(x) & \xrightarrow{y=\Lambda(x):=-\ln(x/p)} & T(y) = \gamma y + G(y) \end{array}$$

Key idea: a change of variables from Liz, 2007.

$$\begin{array}{ccc} x_{n+1} = F(x_n) & \xrightarrow{y=\Lambda(x):=-\ln(x/p)} & y_{n+1} = T(y_n) \\ F(x) = x^\gamma H(x) & & T(y) = \gamma y + G(y) \end{array}$$

Here, $G(y) := -\ln(p^{\gamma-1}H(pe^{-y}))$.

$\Lambda : (0, \infty) \rightarrow \mathbb{R}$ is a **topological conjugacy** between both equations

$$\Lambda \circ F = T \circ \Lambda.$$

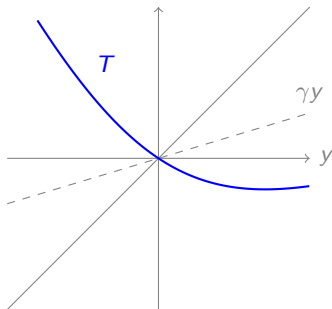
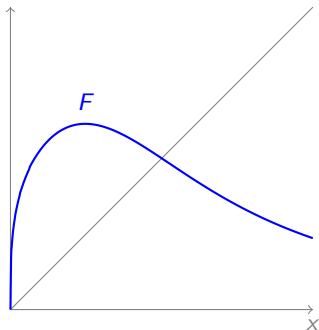
Key idea: a change of variables from Liz, 2007.

$$\begin{array}{ccc} x_{n+1} = F(x_n) & \xrightarrow{y=\Lambda(x):=-\ln(x/p)} & y_{n+1} = T(y_n) \\ F(x) = x^\gamma H(x) & & T(y) = \gamma y + G(y) \end{array}$$

Here, $G(y) := -\ln(p^{\gamma-1}H(pe^{-y}))$.

$\Lambda : (0, \infty) \rightarrow \mathbb{R}$ is a **topological conjugacy** between both equations

$$\Lambda \circ F = T \circ \Lambda.$$



$$x_{n+1} = x_n^\gamma H(x_n), \quad H \text{ is decreasing and } \mathcal{C}^3 \quad (D)$$

Theorem (Liz & B.-F., 2019)

Let $\gamma \in [0, 1]$ and assume that the following condition holds:

$$x^2 \left(2SH(x) + \left(\frac{H'(x)}{H(x)} \right)^2 \right) < 1, \quad \forall x > 0. \quad (*)$$

Then, the local asymptotic stability of the unique positive equilibrium p in equation (D) implies its global stability. This stability condition is

$$-p^\gamma H'(p) \leq 1 + \gamma.$$

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau)) \quad (E)$$

$$\gamma \in [0, 1], h : [0, \infty) \rightarrow (0, \infty) \text{ decreasing and } \mathcal{C}^3$$

$$x_{n+1} = x_n^\gamma H(x_n), \quad H = h/a$$

γ -Mackey-Glass DDE (also for $m \neq 1$): $h(x) = \frac{\beta}{1 + \delta x^m}$

$$H(x) = \frac{\beta/a}{1 + \delta x^m}, \quad SH(x) = \frac{1 - m^2}{2x^2}, \quad \frac{H'(x)}{H(x)} = \frac{-\delta m x^{m-1}}{1 + \delta x^m}.$$

Thus, the new Schwarzian-type condition (*) holds:

$$x^2 \left(2SH(x) + \left(\frac{H'(x)}{H(x)} \right)^2 \right) = 1 - m^2 + m^2 \left(\frac{\delta x^m}{1 + \delta x^m} \right)^2 < 1, \quad \forall x > 0$$

$$x'(t) = -ax(t) + x^\gamma(t - \tau) h(x(t - \tau)) \quad (E)$$

$$\gamma \in [0, 1], h : [0, \infty) \rightarrow (0, \infty) \text{ decreasing and } C^3$$

$$x_{n+1} = x_n^\gamma H(x_n), \quad H = h/a$$

γ -Mackey-Glass DDE (also for $m \neq 1$): $h(x) = \frac{\beta}{1+\delta x^m}$

Theorem (Liz & B.-F., 2019)

Let p be the unique positive equilibrium of equation (E). If

$$m \leq 1 + \gamma \text{ or } \left[m > 1 + \gamma, \quad \frac{\beta}{a} \leq \frac{m}{m-1-\gamma} \left(\frac{\gamma+1}{\delta(m-1-\gamma)} \right)^{\frac{1-\gamma}{m}} \right],$$

then

$$\lim_{t \rightarrow \infty} x(t; \phi) = p, \quad \forall \phi \in C_{(0, \infty)}.$$

The former is the **sharpest delay-independent stability condition** for (E).

Further comments:

- Another way to write (*) was suggested by V. Jiménez-López:

$$SH(x) < \frac{H(x) - xH'(x)}{2(xH(x))^2} (xH(x))', \quad \forall x > 0. \quad (*)$$

- Our result can be adapted to $\gamma = 0$ in order to complement the classical Allwright-Singer one. Note that $F(x) = x^0 H(x) = H(x)$.

Theorem ($\gamma = 0$; Liz & B.-F., 2019)

Assume that the \mathcal{C}^3 map $F : (0, \infty) \rightarrow (0, \infty)$ has at most one critical point c , which would be a local extremum, and $(F(x) - x)(x - p) < 0$ on $(0, \infty) \setminus \{p\}$.

If $F'(p) \geq -1$ and () holds for all $x > 0$ such that $F'(x) \neq 0$, then p is globally attracting for*

$$x_{n+1} = F(x_n).$$

Systems of DDEs

$$x_i'(t) = -x_i(t) + f_i(x_1(t - \tau), \dots, x_s(t - \tau)), \quad \forall i \in \{1, \dots, s\},$$

$$[x_{n+1}]_i = f_i([x_n]_1, \dots, [x_n]_s), \quad \forall i \in \{1, \dots, s\}.$$

DDEs with integral production terms

$$x'(t) = -a(t)x(t) + \int_{\sigma}^t \eta(t, s)x(\nu(s)) ds, \quad t \geq \sigma,$$

Joint work with Rosana Rodríguez López (USC)

Impulsive periodic DDEs

$$\begin{cases} x'(t) = -a(t)x(t) + g(t, x_t), & t \geq 0, t \neq t_k, k \in \mathbb{N}, \\ x(t_k^+) - x(t_k) = I_k(x(t_k)), & k \in \mathbb{N}, \end{cases}$$

Joint work with Teresa Faria (Univ. Lisboa)



This project has been mainly funded by the former **Ministerio de Educación, Cultura y Deporte** of the Government of Spain, under fund number FPU16/04416.

The former Consellería de Cultura, Educación e Ordenación Universitaria of Xunta de Galicia has partially funded this work, under fund number ED481A-2017/030.



Special thanks to our research group Nonlinear Differential Equations and to both CMAF-CIO (Univ. Lisboa) and Bolyai Institute (Univ. Szeged) for supporting the attendance to conferences and my internships.