Dynamics Near the Librations Points

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Recent Trends in Nonlinear Science

Universitat de les Illes Balears

January 21-25, 2019

Course Content

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The slides of the lectures will not be published in the RTNS workshop webside. If you are interested in them, please put in touch with either Elena Fantino (elena.fantino@kustar.ac.ae) or Gerard Gómez (gerard@maia.ub.es)

Lecture I. The *n*-body problem, the restricted *n*-body problem and other restricted models

- I.1 The *n*-body problem
 - 1.1.1 The general *n*-body problem
 - 1.1.2 The *n*-body problem as a perturbation of Kepler's problem
 - 1.1.3 The *n*-body problem as an autonomous Hamiltonian system
- I-2 Autonomous models of the *n*-body problem (n = 3)
 - I.2.1 The restricted 3-body problem (RTBP)
 - 1.2.2 Equilibrium points and zero-velocity surfaces (curves)
 - I.2.3 The restricted 3-body problem as an autonomous Hamiltonian system

- I.2.4 A limit case: Hill's problem
- 1.2.5 The restricted 3-body problem for a solar sail
- 1.3 Non-autonomous models of the *n*-body problem
 - I.3.1 The bicircular 4-body problem (BCP)
 - I.3.2 The quasi-bicircular 4-body problem (QBCP)
 - 1.3.3 The *n*-body problem as a perturbation of the RTBP

Lecture I. References

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Lecture II. Computational tools. Equilibrium points, periodic and quasi-periodic orbits

- 2.1 Continuous and discrete dynamical systems
- 2.2 Equilibrium and fixed points
- 2.3 Periodic orbits
- 2.4 2D Invariant tori
- 2.5 Computation of stable and unstable invariant manifolds

2.6 Dynamical substitutes of the equilibrium points

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Lecture III. Computational tools. The Lindstedt-Poincaré method. Applications

- 3.1 Problem setting and an academic example
- 3.2 Application of the LP method to the CR3BP

- 3.3 Lissajous orbits
- 3.4 Halo orbits
- 3.5 Quasi-halo orbits
- 3.6 Orbits and manifolds
- 3.7 Elliptic HCW equations

Lecture III. References

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Lecture V. The phase space around the equilibrium points of the CR3BP

- V.1 The equilibrium points of the circular restricted 3-body problem
- V.2 The linear dynamics around the collinear equilibrium points
- V.3 The linear dynamics around the equilateral equilibrium points

- V.4 Nonlinear dynamics near the collinear points
- V.5 Reduction to the centre manifold
- V.6 The triangular equilibrium points

Lecture V. References

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